

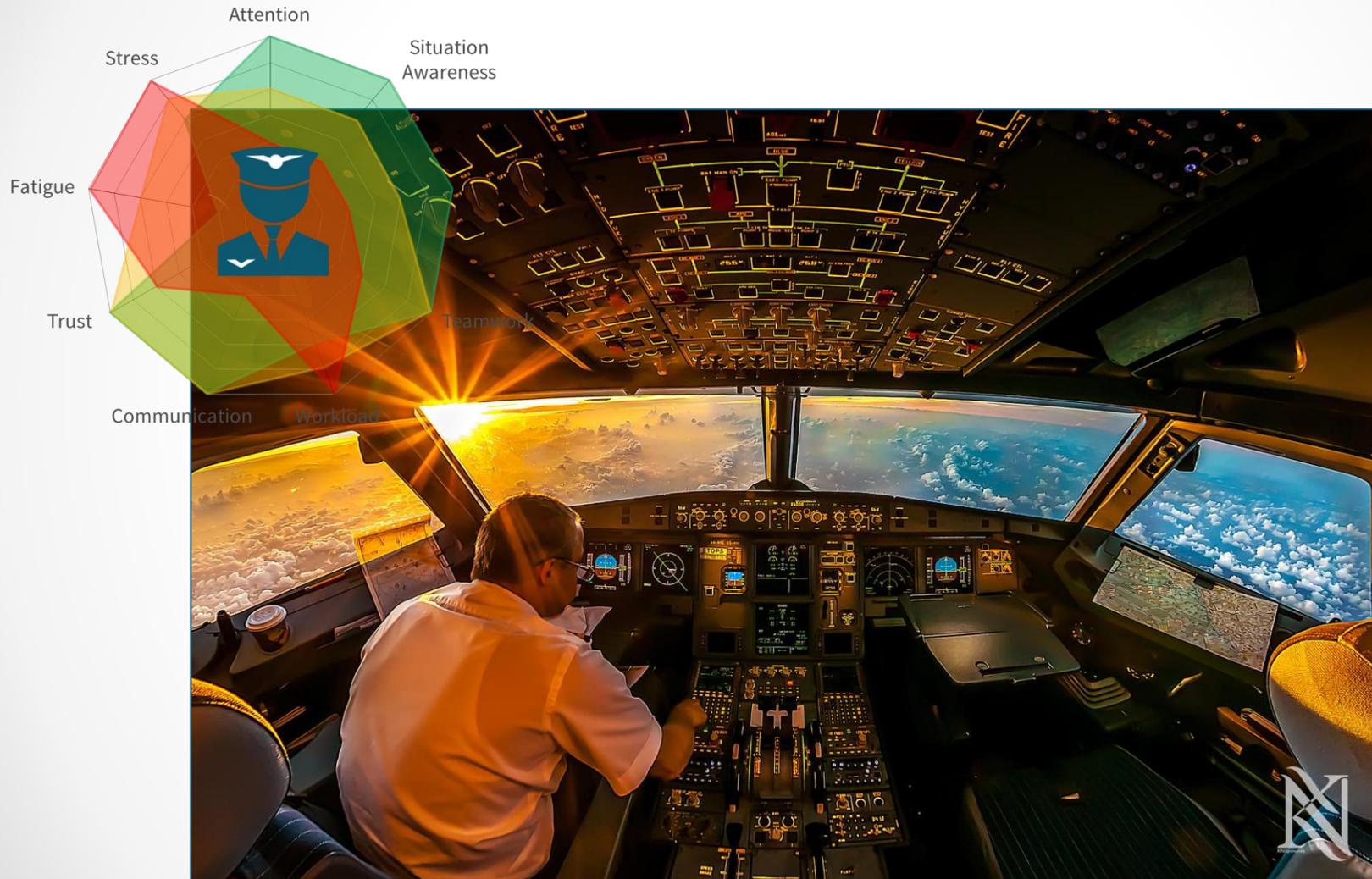
THE FUTURE PILOT FOR THE FUTURE SKY

Frederik Mohrmann, NLR



HPE IN OPERATIONS

Project #6
HUMAN
PERFORMANCE
ENVELOPE





HOW DOES THE HPE CONCEPT
WORK IN AN OPERATIONAL
SCENARIO?

WHERE ARE THE PERFORMANCE
LIMITS OF THE HPE MODEL?

HOW CAN WE SUPPORT THE HPE
EFFECTIVELY?



SCENARIO
DESIGN



PERFORMANCE
METRICS

PHYSIO METRICS
& MENTAL
REPRESENTATION

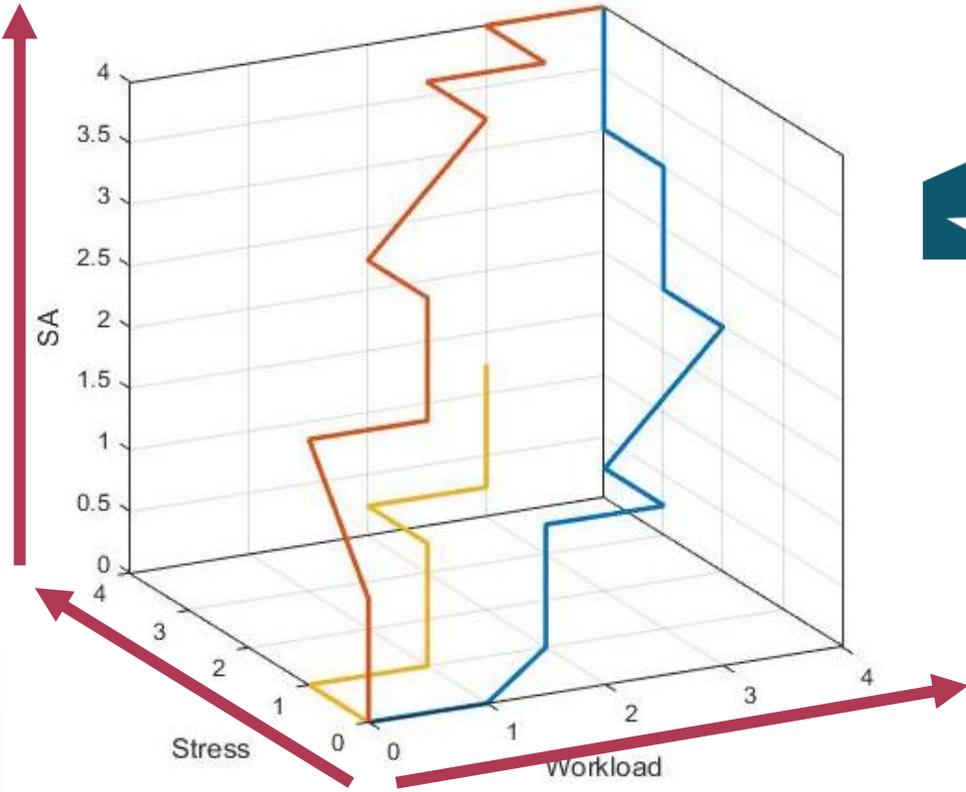
EXPERIMENT

RESULTS

OUR NEXT
STEPS



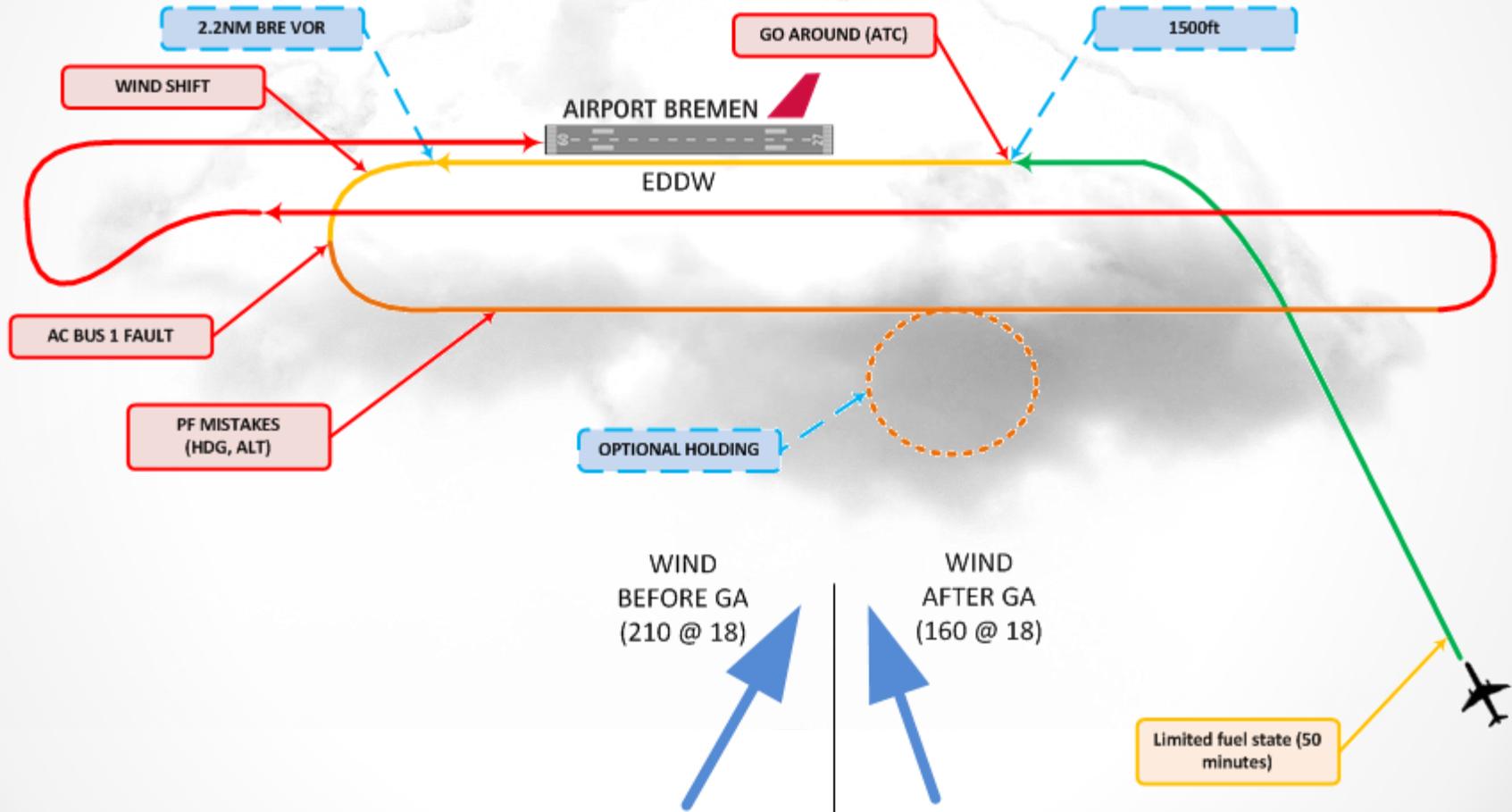
WL	ST	SA
0	0	0
0	0	1
0	0	1
0	0	1
0	0	1
0	0	1
0	0	2
0	0	2
0	1	2
1	0	3
1	0	3
1	0	3
1	0	2
1	0	3
1	0	3
1	0	3
0.5	0	1.5
0.5	1	2.5
1.5	1	2.5
1.5	1	1.5
1.5	1	1.5
1.5	1	1.5
1.5	1	1.5
2.5	2	2.5
2.5	1	2.5
2.5	1	2.5
2.5	1	2.5
3.5	1	3.5
3.5	1	3.5
2.5	1	2.5
2.5	2	3.5
3.5	2	3.5
3.5	2	3.5
3.5	2	3.5
3.5	2	4.5
3.5	3	4.5
3.5	3	4.5
3.5	3	4.5
3.5	3	4.5
3.5	3	4.5
3.5	3	4.5
3.5	3	4.5
3.5	3	4.5
3.5	3	4.5
3.5	3	4.5
3.5	3	4.5
4.5	4	4.5
4.5	4	4.5
4.5	5	5.5
4.5	4	5.5
4.5	4	5.5
4.5	4	5.5
4.5	4	5.5
4.5	4	5.5



**PILOT
FLYING**



**PILOT
MONITORING**





ELEC AC BUS 1 FAULT

AC BUS 1 normally supplies the AC ESS BUS and, through TR1, the DC ESS BUS. In case of an AC BUS 1 FAULT both the AC and DC ESS BUS will be lost and therefore the AC ESS BUS FAULT and the DC ESS BUS FAULT will be displayed on the ECAM. However, both AC and DC ESS BUS can be recovered by switching the AC ESS FEED pushbutton to ALTN as displayed in the AC ESS BUS FAULT ECAM procedure.

- BLOWER OVRD
The avionics ventilation system is in the closed circuit configuration.
Air conditioning is added to the ventilation air.

WHEEL N.W. STEER FAULT

VENT EXTRACT FAULT

- EXTRACT OVRD

ENG 1 EPR MODE FAULT

Refer to associated procedure

- Affected systems**
- * AVNCS VENT
 - * HYD
 - * FUEL
 - * F/CTL

ELEC AC BUS 1 FAULT (CONT'D)

STATUS

- LDG DIST PROC APPLY | INOP SYS
Refer to the QRH Part 2, or to the FCOM 3.02.80. | See below

CAB ZONE AT FIXED TEMP

Due to the loss of the galley fan, the Pack 1 controller, and the primary zone controller channel. (See associated procedures).

STARTS DOWN CAT 2 ONLY

INOP SYS displayed on ECAM

BLUE HYD	L+R TK PUMP 1	MAIN GALLEY
SPLR 3	CTR TK PUMP 1	B ELEC PUMP
ADR 3	VENT BLOWER	BSCU CH 1
RA 1	GALLEY FAN	DMC 3
CAPT TAT	CRG VENT <4	GPWS
L WSHLD HEAT	GND COOL <4	LAV DET
L WNDW HEAT	N.W. STEER	PACK 1 REGUL
CAT 3	REVERSER 1	

Other inoperative systems

Left cabin fan	Engine 1 ignition B	Zone controller prim channel
Radar 1	EVMU eng 1 and eng 2	Hydraulic quantity indication
Stby Pitot/AOA	Printer	Partial galley
ACARS <4	MCDU 3 <4	PVI <4
Brake fans 5, 6, 7 and 8 <4		TCAS <4
HUD <4		

Note : The warning may be caused by a sub BUS failure. Consequently, only a part of the above-listed systems may be lost.



INITIAL APPROACH



GO AROUND WITH LIMITED FUEL



AC BUS 1 FAILURE & PF MISTAKES



SECOND GO AROUND (WIND SHIFT)



LANDING WITH LOW FUEL, WINDSHEILD FROZEN

WL	ST	SA
0	0	0
0	0	1
0	0	1
0	0	1
0	0	1
0	0	2
0	0	2
0	1	2
1	0	3
1	0	3
1	0	3
1	0	3
1	0	3
0.5	0	1.5
1.5	1	2.5
1.5	1	1.5
1.5	1	1.5
1.5	1	1.5
1.5	1	1.5
2.5	2	2.5
2.5	1	2.5
2.5	1	2.5
2.5	1	2.5
3.5	1	3.5
3.5	1	3.5
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3.5	3	4.5
3.5	3	4.5
3.5	3	4.5
3.5	3	4.5
4.5	4	4.5
4.5	4	4.5
4.5	5	5.5
4.5	4	5.5
4.5	4	5.5
4.5	4	5.5
4.5	4	5.5



SCENARIO
DESIGN

PERFORMANCE
METRICS

PHYSIO METRICS
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REPRESENTATION

EXPERIMENT

RESULTS

OUR NEXT
STEPS



ICAO DOC 9995

EVIDENCE BASED TRAINING

(COMPETENCY BASED TRAINING)

**Situational
Awareness**

**Problem Solving &
Decision Making**

**Application of
Procedures**

HPE-sensitive

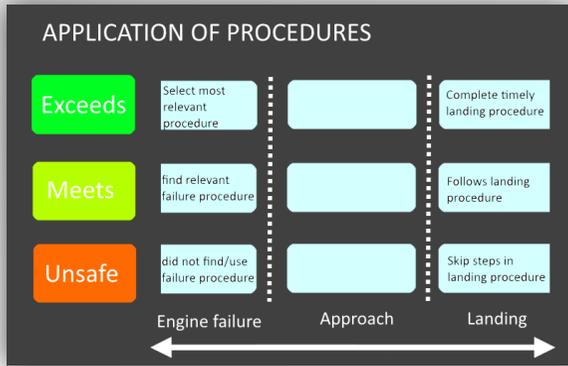
Single-pilot

PM relevant

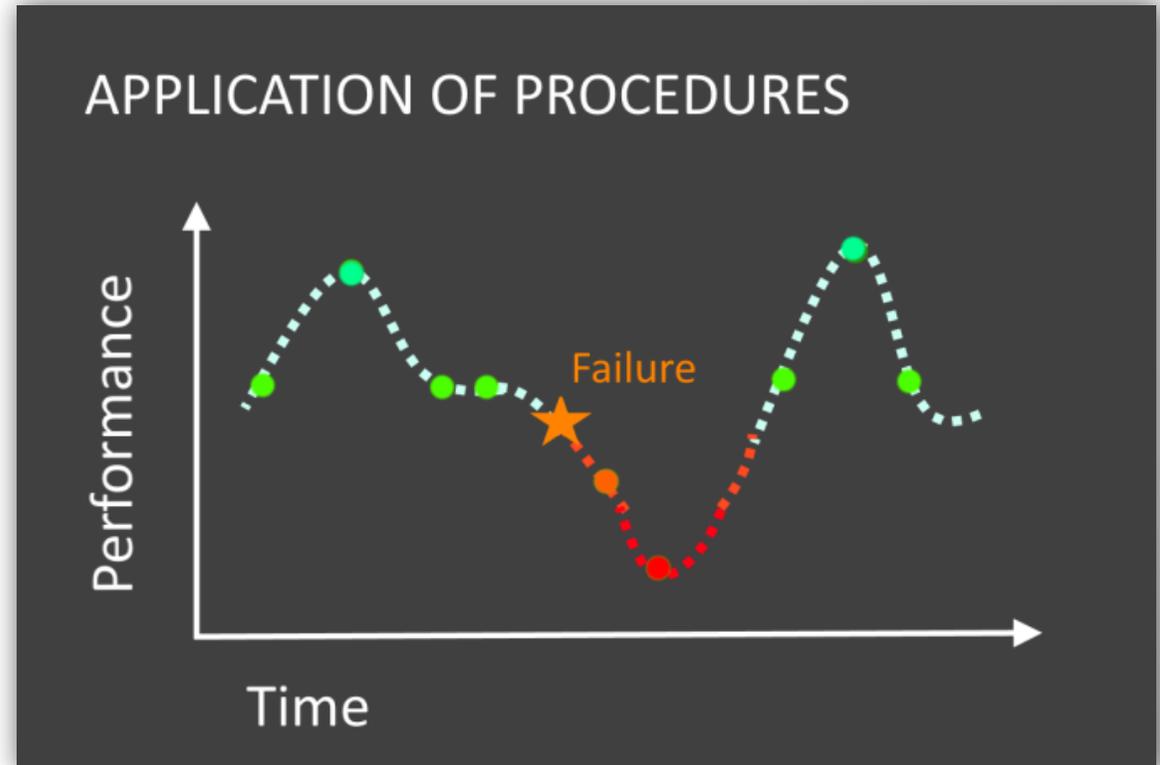
Observable



		General	Descent & Approach 27	Go around	AC BUS FAULT	Second LAPA calc (RWY)	Approach	
Situational Awareness	Identifies and assesses accurately the state of the aircraft(systems), aircraft position, environment, and of people involved and anticipates on what could happen in the future.	1 Exceeds	Develops 'what if' scenarios and plans for contingencies, including further anticipation of the far future.	Interprets and what-if scenarios, options, updates throughout the descent	Notifies status, wind shift and PF errors. Interprets and what-if scenarios, suggests courses of action	Realises it is a OM-B inop problem and its consequences	Identifies potential hazards that can evolve as a result of condition (Mentions extra space in front of the runway, and potential nose wheel steering issues), e.g. runway overrun and subsequent evacuation	
		2 Meets	Has an awareness of the aircraft state in its environment (including people); projects to near future and anticipates changes.	Mentions fuel/endurance in minutes	Notifies fuel status, wind shift and PF errors.	Verbalises consequences for Landing dist.	Acknowledges runway state, fuel state, weather. Mentions potential nose wheel steering problem	
		3 Below	Spends time searching for irrelevant information, incomplete assessment of the situation.	Mentions fuel/endurance in kilos/tons	Does not notice one of the three events	Does not mention fuel, and/or landing dist	Accepts additional inputs from ATC without actively seeking new information. QRH awareness, Mentions CAT1 landing	Requires extra time to complete the picture of the situation
		4 Unacceptable	Does not or incorrectly identify the state (changes), does not seek updates.	No mention of fuel status	Does not notice two of three events, or all	Misses two of the three issues or all	Slow in accepting new information. Misses QRH and/or CAT1 issue.	Misses urgency of the situation
Decision making	Identifies the problem and diagnoses, identifies risks, generates options, decides, resolves problems, monitors, and evaluates.	1 Exceeds	Anticipates future states, effects and risks, is pro-active.		Demonstrates knowledge (Realises it is a OM-B inop issue) of AC BUS fault consequences	Anticipated possible weather deterioration in relation with landing runway	Prepares for potential contingencies. Requests full help of emergency vehicles, prepares cabin, dedicates for landing etc.	
		2 Meets	Evaluates (potential) problems, identifies risk, considers alternatives and selects the best course of action. Continuously reviews progress and adjust plans.		Understands the consequences once read from ECAM/OM. Realises it is a OM-B inop issue	Combines technical failure with changes weather situation, decided on landing 09	Accepts information and identifies the criticality of the situation: low fuel, relatively short runway, bad weather	
		3 Below	Evaluates the problem poorly. Makes decisions based on incomplete information.		Does not combine the consequence with operational status (landing dist, 27 potentially too short with tailwind, 09 longer flying time considering low fuel)	Passive in decision making, leaves the decision to ATC or PF	Misses elements, e.g. briefs go-around i.s.o. dedicating to landing	
		4 Unacceptable	Does not identify there is a problem. Does not indicate what must be done. Does not adjust plan where necessary.		Proposes course of action not taking into account both anomalies	Does not decide on runway 09 as best option for landing	Suggests wrong actions, e.g. not using maximum stopping performance, possibly making a go-around	
Application of procedures	Identifies and applies accurately procedures in accordance with published operating instructions and applicable regulations, using the appropriate knowledge. Only if a higher degree of safety is achieved, deviation from standard procedures might be necessary.	1 Exceeds	Identifies and applies at the correct moment the procedures according to published operating instructions.	Mentions threats and errors, defines mitigating measures		Demonstrates knowledge of AC BUS fault procedure, anticipates time available vs procedure length	Mentions threats and errors, defines mitigating measures. All preparations and checklists completed well in time	
		2 Meets	Execute the prescribed procedures and operate the systems during normal and abnormal circumstances.	Briefing, approach preparation incl landing dist calc, approach checklist	Performs actions and call-outs (gear, flaps, ATC comms)	call for ECAM actions	Correctly calculates landing distance. After discussion identifies consequences. Uses Mayday call	Briefing, approach preparation, approach checklist. Time management in relation with time pressure
		3 Below	Applies in general the procedures according to published operating instructions. Unnecessarily skips procedure steps.	Misses steps, caught by approach checklist	Slow in actions, gear, flaps, ATC comms	Slow in call for ECAM actions	Calculates LAPA, but initially with some errors that are corrected	Misses steps, caught by checklist or ECAM Status. Takes extra time to complete the procedure
		4 Unacceptable	Follows the wrong procedure. Skips important procedure steps. Or follows the procedure in such a way that the result is influenced negatively.	Misses essential threats (RWY length, weather, fuel)		Forgets to fly the aircraft, misses procedure steps (status page, OM ref)	Incorrect calculation, wrong result	Misses essential threats (runway length, runway state, fuel status, weather) in the briefing

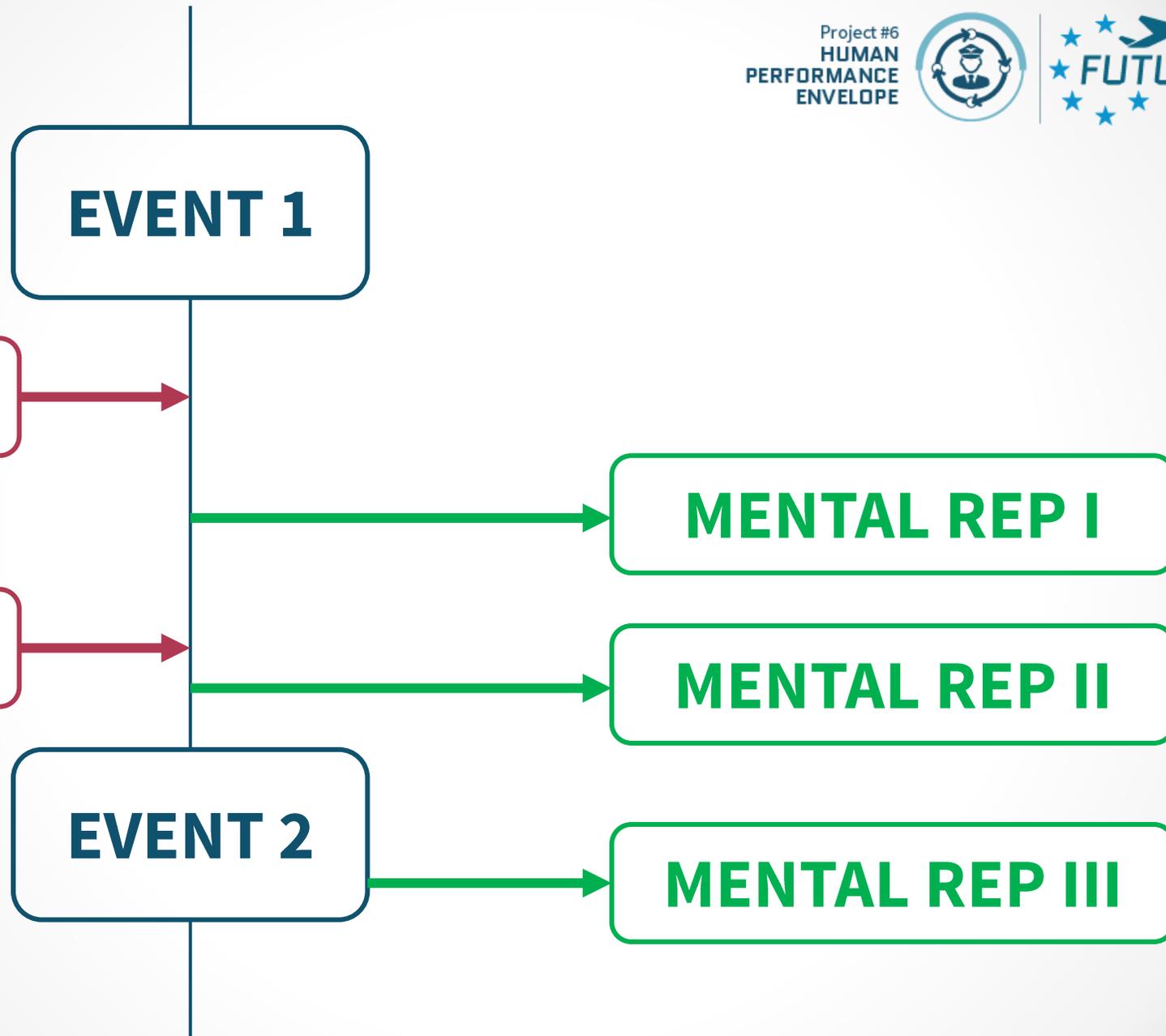


ONLINE
TOOL











SCENARIO
DESIGN

PERFORMANCE
METRICS

PHYSIO METRICS
& MENTAL
REPRESENTATION

EXPERIMENT

RESULTS

OUR NEXT
STEPS



AVES SIMULATOR @ DLR

ONLINE ASSESSMENT @ NLR

The screenshot displays the 'FutureSky Safety' web application. On the left, there is a list of tasks categorized into three sections: 'Situational Awareness', 'Problem solving and Decision making', and 'Application of procedures'. Each task has a corresponding performance level indicator (Excellent, Above, Below, Unacceptable) shown as a colored bar. On the right, a video player shows a scene from the Aves simulator. Below the video player, there are navigation buttons: 'INSTRUCTIONS PAGE', 'COMPETENCY MATRIX (PDF)', 'SCENARIO OVERVIEW (PDF)', and 'FULLSCREEN'. The video player shows a progress bar at 00:15:31 / 00:37:06 and a 'Press icon to test' button.

Task Description	Performance Level
Develops what if scenarios and plans for contingencies, including further anticipation of the future.	Excellent
Has an awareness of the aircraft state in its environment (including people); projects to near future and anticipates changes.	Above
Spends time searching for <u>relevant</u> information, incomplete assessment of the situation	Below
Does not or incorrectly identify the state (changes), does not <u>test</u> updates	Unacceptable
Problem solving and Decision making	
Anticipates future states, effects and risks, is <u>proactive</u>	Excellent
Evaluates (potential) problems, identifies risk, considers alternatives; and selects the best course of action; <u>continuously</u> assesses progress and adjust plans	Above
Evaluates the problem <u>poorly</u> . Makes decisions based on <u>incomplete</u> information	Below
Does not <u>diagnose</u> there is a problem. Does not <u>analyze</u> what must be done. Does not <u>adjust</u> plan where necessary	Unacceptable
Application of procedures	
Identifies and applies at the <u>appropriate</u> the procedures according to published operating instructions	Excellent
<u>Execute</u> the prescribed procedures and operate the systems during normal and abnormal circumstances	Above
Applies in general the procedures according to published operating instructions. <u>Unnecessarily</u> skips procedure steps	Below
Follows the <u>wrong</u> procedure. Skips important procedure steps. Or follows the procedure in such a way that the result is <u>unintended</u> operations	Unacceptable



@ DLR

Project #6
HUMAN
PERFORMANCE
ENVELOPE




FUTURE SKY
SAFETY



**PILOT
FLYING
(CAPTAIN)**

**SCRIPTED
ROLE**



**PILOT
MONITORING
(FIRST OFFICER)**

**CANDIDATE
PILOT**



@ NLR

Project #6
HUMAN
PERFORMANCE
ENVELOPE



FUTURE SKY
SAFETY

Three competencies

Situational Awareness

Develops what if scenarios and plans for contingencies, including further anticipation of the far future	Exceeds
Has an awareness of the aircraft state in its environment (including people); projects to near future and anticipates	Meets
Spends time searching for irrelevant information, incomplete assessment of the situation	Below
Does not or incorrectly identify the state (changes), does not seek updates	Unacceptable

Problem solving and Decision making

Anticipates future states, effects and risks, is pro-active	Exceeds
Evaluates (potential) problems, identifies risk, considers alternatives and selects the best course of action. Continuously reviews progress and adjust plans	Meets
Evaluates the problem poorly. Makes decisions based on incomplete information	Below
Does not identify there is a problem. Does not indicate what must be done. Does not adjust plan where necessary	Unacceptable

Application of procedures

Identifies and applies at the correct moment the procedures according to published operating instructions	Exceeds
Execute the prescribed procedures and operate the systems during normal and abnormal circumstances	Meets
Applies in general the procedures according to published operating instructions. Unnecessarily skips procedure steps	Below
Follows the wrong procedure. Skips important procedure steps. Or follows the procedure in such a way that the result is influenced negatively	Unacceptable

Flight Scenario Video



Track your ratings



00:20:48 / 00:42:54



Press icon to test

Play and Pause only

Test your sound (!)



FOUR FLIGHT INSTRUCTORS

OVER THE SUMMER

ALL CREWS RATED

(4/10 MULTI-RATED)



SCENARIO
DESIGN

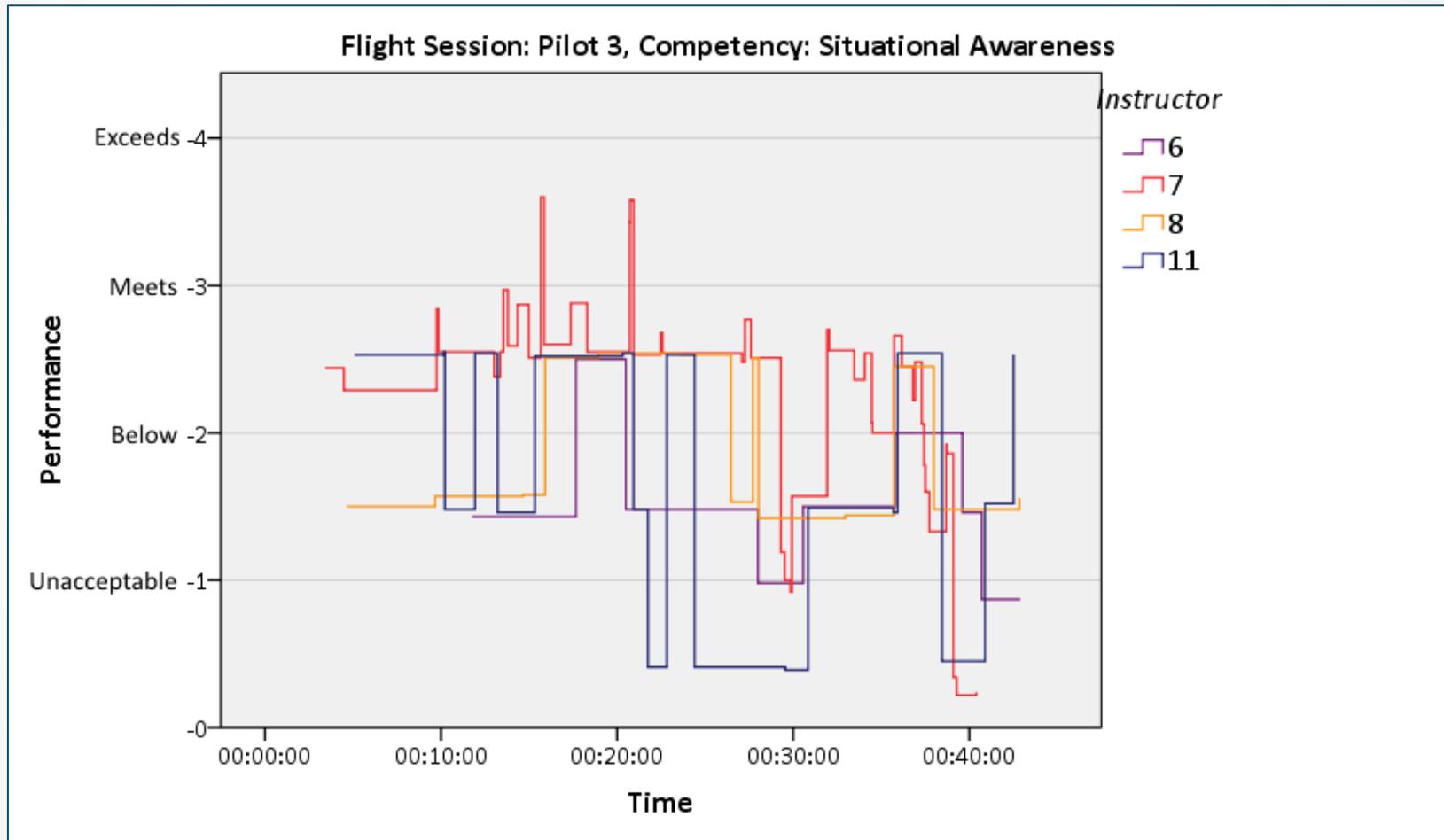
PERFORMANCE
METRICS

PHYSIO METRICS
& MENTAL
REPRESENTATION

EXPERIMENT

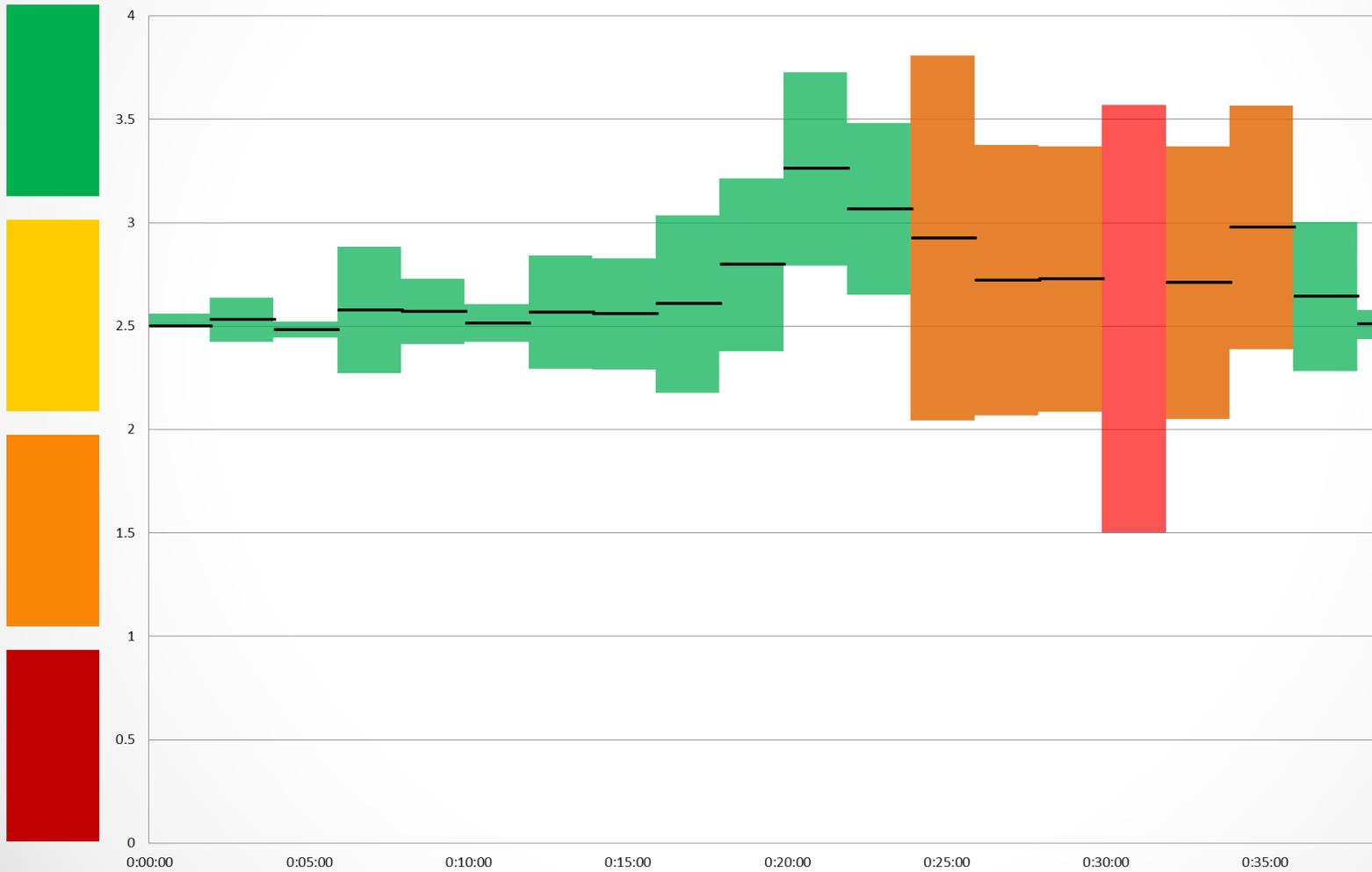
RESULTS

OUR NEXT
STEPS



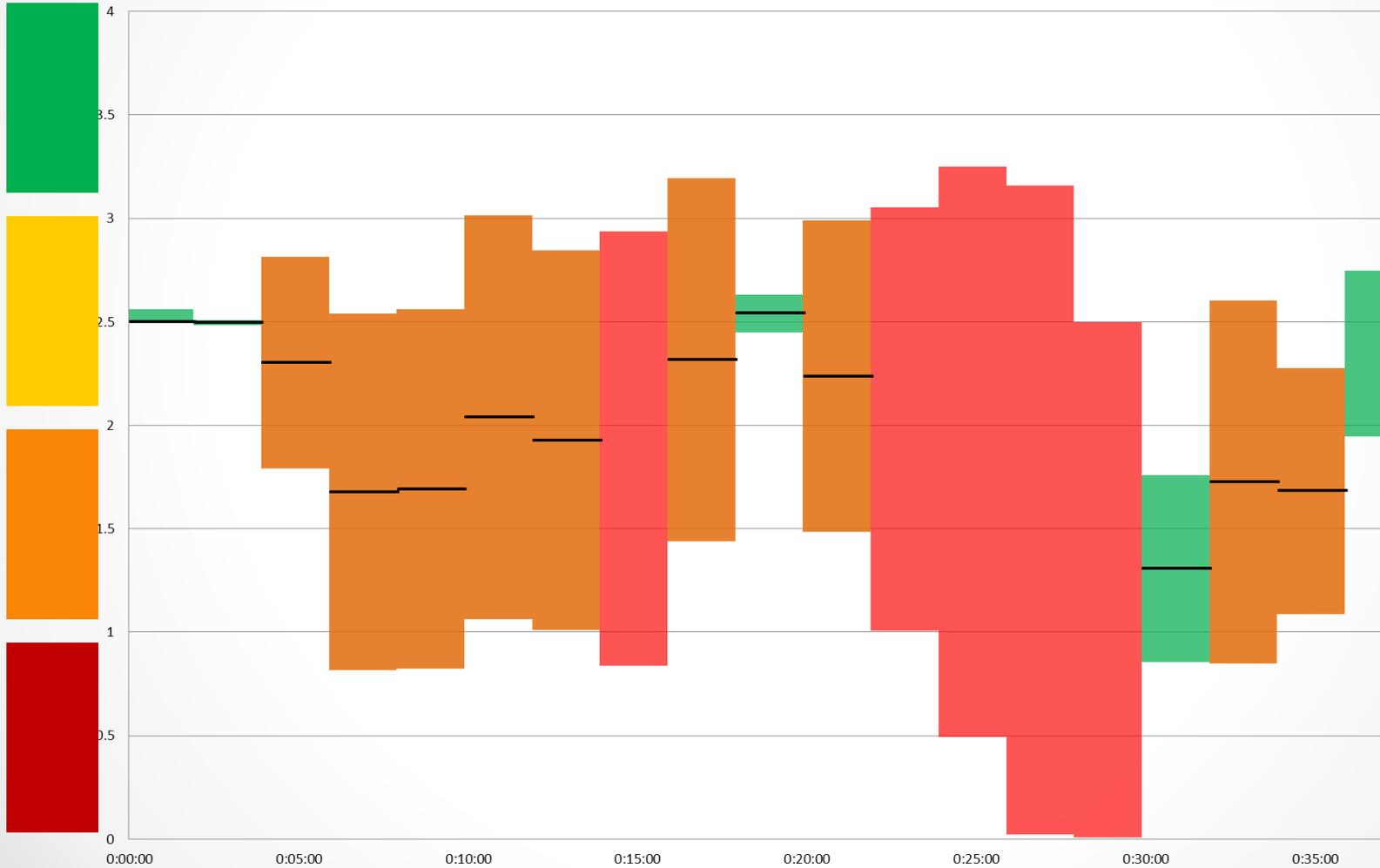


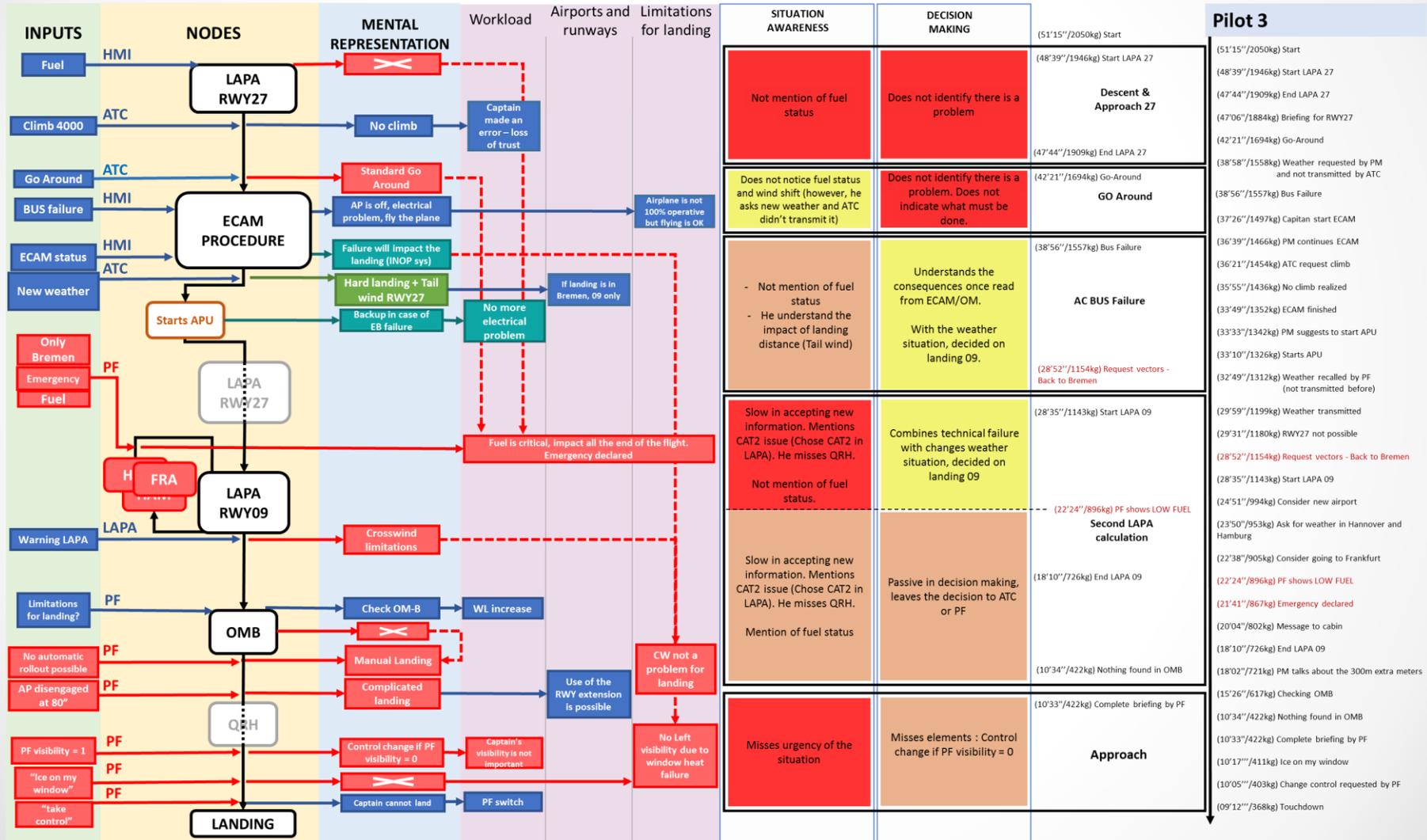
Pilot 10 DM (Data distribution spread, Resolution 2 min)





Pilot 4 SA (Data distribution spread, Resolution 2 min)







SCENARIO
DESIGN

PERFORMANCE
METRICS

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REPRESENTATION

EXPERIMENT

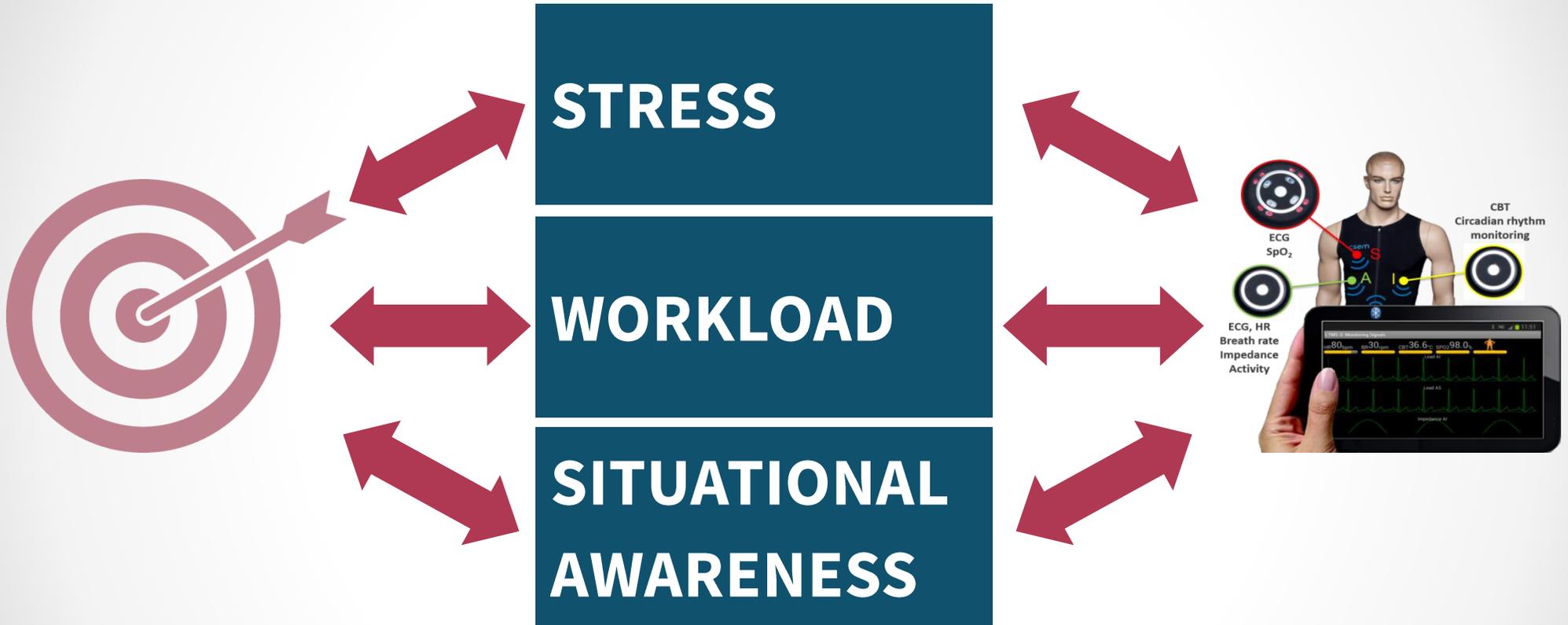
RESULTS

OUR NEXT
STEPS

SCENARIO 1



Project #6
HUMAN
PERFORMANCE
ENVELOPE



Performance =

$$.354 * (25.935 * \mathbf{HR} + 41.075 * \mathbf{EYE} - 61.495) + .285 * (28.928 * \mathbf{HR} + 44.242 * \mathbf{EYE} - 68.747) + -.446 * (-42.2185 * \mathbf{HR} + 31.697) + .313 * (25.935 * \mathbf{HR} + 41.075 * \mathbf{EYE} - 61.495) * (28.928 * \mathbf{HR} + 44.242 * \mathbf{EYE} - 68.747) * (-42.2185 * \mathbf{HR} + 31.697)$$



SCENARIO 1



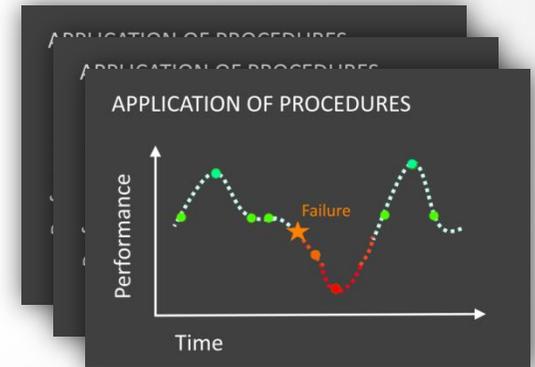
PREDICTED
PERFORMANCE

VALIDATE
HPE EQUATION

SCENARIO 2



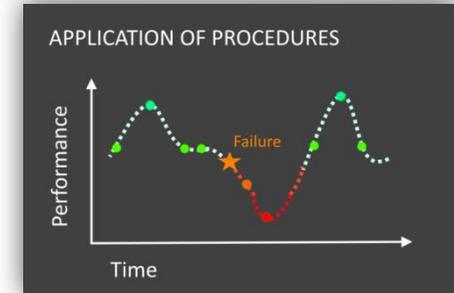
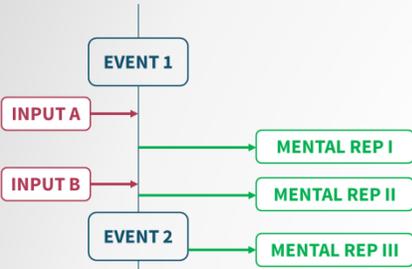
SCENARIO 2





Inputs	Standad Phase	Notes	Pilot 1	Pilot 2	Pilot 3	Pilot 4	Pilot 5	Pilot 6	Pilot 7	Pilot 8	Pilot 9	Pilot 10
Fuel	Descent & Approach 27	LAPA RWY27	Red	Red	Red	Red	Red	Red	Red	Red	Red	Red
Fuel + Climb4000	GO Around	Climb4000	Red	Blue	Blue	Red	Blue	Grey	Blue	Blue	Blue	Blue
Fuel + GoAround		GO Around (Critical fuel)	Cyan	Cyan	Red	Cyan	Cyan	Red	Red	Cyan	Red	Cyan
Fuel + BUS Failure + ECAM status	AC BUS Failure	ECAM PROCEDURE	Cyan	Cyan	Red	Green	Cyan	Cyan	Blue	Cyan	Cyan	Green
Fuel + New weather + Airports status		CONSIDER NEW AIRPORT (FUEL)	Red	Red	Red	Red	Blue	Red	Blue	Blue	Blue	Green
Fuel + RWY27 not possible		RWY SHIFT (WIND)	Red	Red	Cyan	Red	Red	Blue	Blue	Red	Red	Blue
Warning LAPA	Second LAPA calculation	LAPA RWY09 (Warning)	Blue	Cyan	Red	Blue	Red	Blue	Cyan	Blue	Blue	Blue
Limitations for landing? + No automatic rollout possible + AP disengaged at 80"	Approach	OMB (Knowledge about landing limitations)	Cyan	Cyan	Red	Cyan	Cyan	Cyan	Cyan	Red	Blue	Blue
PF visibility must be = 1		QRH (Awareness about PF visibility = 1)	Red	Blue	Red	Green	Blue	Green	Blue	Blue	Cyan	Blue
"Ice on my window"		LANDING	Red	Blue	Red	Blue	Blue	Blue	Blue	Blue	Blue	Blue

		Pilot 1	Pilot 2	Pilot 3	Pilot 4	Pilot 5	Pilot 6	Pilot 7	Pilot 8	Pilot 9	Pilot 10
Descent & Approach 27	LAPA RWY27	Red	Red	Red	Red	Red	Red	Red	Red	Red	Red
GO Around	Climb4000	Red	Green	Green	Red	Green	Grey	Green	Green	Green	Green
	GO Around (Critical fuel)	Red	Red	Red	Red	Red	Red	Red	Red	Red	Red
AC BUS Failure	ECAM PROCEDURE	Red	Red	Red	Green	Red	Red	Red	Red	Red	Red
	CONSIDER NEW AIRPORT (FUEL)	Red	Red	Red	Red	Green	Red	Red	Red	Red	Red
	RWY SHIFT (WIND)	Red	Red	Red	Red	Red	Red	Red	Red	Red	Red
Second LAPA calculation	LAPA RWY09 (Warning)	Green	Red	Red	Red	Red	Red	Red	Red	Red	Red
Approach	OMB (Knowledge about landing limitations)	Red	Red	Red	Red	Red	Red	Red	Red	Red	Red
	QRH (Awareness about PF visibility = 1)	Red	Green	Red	Green	Red	Red	Red	Red	Red	Red
	LANDING	Red	Green	Red	Red	Red	Red	Red	Red	Red	Red



Inputs	Standard Phase	Notes	Plot 1	Plot 2	Plot 3	Plot 4	Plot 5	Plot 6	Plot 7	Plot 8	Plot 9	Plot 10
Fuel	Descent & Approach 27	LAPA RWY27										
Fuel + Climb4000	GO Around	Climb4000										
Fuel + G/Around		GO Around (Critical fuel)										
Fuel + BUS Failure + EICAS status	AC BUS Failure	SCAM PROCEDURE										
Fuel + New weather + Airports failure		CONSIDER NEW AIRPORT (FUEL)										
Fuel + RWY27 not possible	Second LAPA calculation	RWY SHIFT (RWNY)										
Warning LAPA		LAPA RWY09 (Warning)										
Limitations for landing + No automatic release possible + AP (Knowledge about PF visibility = 1)	Approach	CMB (Knowledge about landing limitations)										
PF visibility must be + 1		QRH (Awareness about PF visibility = 1)										
"No on my window"	LANDING											

Inputs	Standard Phase	Notes	Plot 1	Plot 2	Plot 3	Plot 4	Plot 5	Plot 6	Plot 7	Plot 8	Plot 9	Plot 10
Fuel	Descent & Approach 27	LAPA RWY27										
Fuel + Climb4000	GO Around	Climb4000										
Fuel + G/Around		GO Around (Critical fuel)										
Fuel + BUS Failure + EICAS status	AC BUS Failure	SCAM PROCEDURE										
Fuel + New weather + Airports failure		CONSIDER NEW AIRPORT (FUEL)										
Fuel + RWY27 not possible	Second LAPA calculation	RWY SHIFT (RWNY)										
Warning LAPA		LAPA RWY09 (Warning)										
Limitations for landing + No automatic release possible + AP (Knowledge about PF visibility = 1)	Approach	CMB (Knowledge about landing limitations)										
PF visibility must be + 1		QRH (Awareness about PF visibility = 1)										
"No on my window"	LANDING											

VALIDATED HMI DESIGN MATRIX

Inputs	Standard Phase	Notes	Plot 1	Plot 2	Plot 3	Plot 4	Plot 5	Plot 6	Plot 7	Plot 8	Plot 9	Plot 10
Fuel	Descent & Approach 27	LAPA RWY27										
Fuel + Climb4000	GO Around	Climb4000										
Fuel + G/Around		GO Around (Critical fuel)										
Fuel + BUS Failure + EICAS status	AC BUS Failure	SCAM PROCEDURE										
Fuel + New weather + Airports failure		CONSIDER NEW AIRPORT (FUEL)										
Fuel + RWY27 not possible	Second LAPA calculation	RWY SHIFT (RWNY)										
Warning LAPA		LAPA RWY09 (Warning)										
Limitations for landing + No automatic release possible + AP (Knowledge about PF visibility = 1)	Approach	CMB (Knowledge about landing limitations)										
PF visibility must be + 1		QRH (Awareness about PF visibility = 1)										
"No on my window"	LANDING											

THE FUTURE PILOT
FOR THE FUTURE SKY....

